

Semantics of programming languages

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Coalgebraic structural operational semantics

- Coalgebra allows to model behavior of program systems.
- Coalgebra defines structural operational semantics of programs written in some programming language.
- Coalgebra is constructed over category of state space by polynomial endofunctor.
- Every application of functor models one step of computation so as structural operational semantics.

Language *Jane*

- We briefly show the structural operational semantics of *Jane*.
- The following syntactic domains are introduced:
 - $n \in \mathbf{Num}$ – strings of digits;
 - $x \in \mathbf{Var}$ – names of variables;
 - $e \in \mathbf{Expr}$ – arithmetic expressions;
 - $b \in \mathbf{Bexpr}$ – Boolean expressions;
 - $S \in \mathbf{Statm}$ – statements.
 - $D \in \mathbf{Decl}$ – declarations of variables.

Syntactic domains **Num** and **Var** do not have internal structure from semantic point of view.

Language *Jane*: Syntax

Syntactic domain **Expr** contains well-formed arithmetic expressions according the following syntactic rule:

$$e ::= n \mid x \mid e + e \mid e - e \mid e * e.$$

Well-formed Boolean expressions from **Bexpr** can be of the following forms:

$$b ::= \text{false} \mid \text{true} \mid e = e \mid e \leq e \mid \neg b \mid b \wedge b.$$

Statements $S \in \mathbf{Statm}$ are standard (basic) Dijkstra's constructs (also called D-diagrams) - variable assignment, empty statement, sequence of statements, conditional statement and loop statement:

$$S ::= x := e \mid \text{skip} \mid S; S \mid \text{if } b \text{ then } S \text{ else } S \mid \text{while } b \text{ do } S.$$

State

- The main semantic domain in structural operational semantics is **State** which contains particular memory states;
- state $s \in \mathbf{State}$ is an abstraction of computer memory;
- each state is considered as function:

$$s : \mathbf{Var} \times \mathbf{Level} \rightarrow \mathbf{Z}.$$

A change of memory content (cell) is represented as an actualization of a state:

$$s' = s[((x, l), v) \mapsto ((x, l), \mathbf{n})].$$

Semantics of expressions

Semantic functions for arithmetic and Boolean expressions, resp., are

$$\llbracket e \rrbracket : \mathbf{Expr} \rightarrow \mathbf{State} \rightarrow \mathbf{Value}$$

$$\llbracket b \rrbracket : \mathbf{Bexpr} \rightarrow \mathbf{State} \rightarrow \mathbf{Bool}$$

$$\llbracket \mathbf{true} \rrbracket s = \mathbf{true}$$

$$\llbracket n \rrbracket s = \mathbf{n}$$

$$\llbracket \mathbf{false} \rrbracket s = \mathbf{false}$$

$$\llbracket x \rrbracket s = \llbracket \mathit{get} \rrbracket (x, s)$$

$$\llbracket e_1 = e_2 \rrbracket s = \begin{cases} \mathbf{true} & \text{if } \llbracket e_1 \rrbracket s = \llbracket e_2 \rrbracket s \\ \mathbf{false} & \text{otherwise} \end{cases}$$

$$\llbracket e_1 + e_2 \rrbracket s = \llbracket e_1 \rrbracket s \oplus \llbracket e_2 \rrbracket s$$

$$\llbracket e_1 \leq e_2 \rrbracket s = \begin{cases} \mathbf{true} & \text{if } \llbracket e_1 \rrbracket s \leq \llbracket e_2 \rrbracket s \\ \mathbf{false} & \text{otherwise} \end{cases}$$

$$\llbracket e_1 - e_2 \rrbracket s = \llbracket e_1 \rrbracket s \ominus \llbracket e_2 \rrbracket s$$

$$\llbracket \neg b \rrbracket s = \begin{cases} \mathbf{true} & \text{if } \llbracket b \rrbracket s = \mathbf{false} \\ \mathbf{false} & \text{otherwise} \end{cases}$$

$$\llbracket e_1 * e_2 \rrbracket s = \llbracket e_1 \rrbracket s \otimes \llbracket e_2 \rrbracket s$$

$$\llbracket b_1 \wedge b_2 \rrbracket s = \begin{cases} \mathbf{true} & \text{if } \llbracket b_1 \rrbracket s = \mathbf{true} \text{ and } \llbracket b_2 \rrbracket s = \mathbf{true} \\ \mathbf{false} & \text{otherwise} \end{cases}$$

Semantics of statements

Semantic function is defined as follows:

$$\llbracket S \rrbracket : \mathbf{Statm} \rightarrow \mathbf{State} \rightarrow \mathbf{State}$$

$$\langle x := e, s \rangle \Rightarrow s[x \mapsto \llbracket e \rrbracket s] \quad (1_{os}) \quad \langle \mathbf{skip}, s \rangle \Rightarrow s \quad (2_{os})$$

$$\frac{\langle S_1, s \rangle \Rightarrow \langle S'_1, s' \rangle}{\langle S_1; S_2, s \rangle \Rightarrow \langle S'_1; S_2, s' \rangle} \quad (3_{os}^1) \quad \frac{\langle S_1, s \rangle \Rightarrow s'}{\langle S_1; S_2, s \rangle \Rightarrow \langle S_2, s' \rangle} \quad (3_{os}^2)$$

$$\frac{\llbracket b \rrbracket s = \mathbf{true}}{\langle \mathbf{if } b \mathbf{ then } S_1 \mathbf{ else } S_2, s \rangle \Rightarrow \langle S_1, s \rangle} \quad (4_{os}^{\mathbf{true}})$$

$$\frac{\llbracket b \rrbracket s = \mathbf{false}}{\langle \mathbf{if } b \mathbf{ then } S_1 \mathbf{ else } S_2, s \rangle \Rightarrow \langle S_2, s \rangle} \quad (4_{os}^{\mathbf{false}})$$

$$\langle \mathbf{while } b \mathbf{ do } S, s \rangle \Rightarrow \langle \mathbf{if } b \mathbf{ then } (S; \mathbf{while } b \mathbf{ do } S) \mathbf{ else skip}, s \rangle \quad (5_{os})$$

Basic notions

- Coalgebra is mathematical structure, that is constructed over a base category by polynomial endofunctor;
- Category \mathcal{C} is a structure, that consists of objects and morphisms between them;
- Functor is a kind of morphism between categories. Functor defined on one category is called endofunctor.

$$F : \mathcal{C} \rightarrow \mathcal{C}$$

The name *polynomial* is used for functor which has a form of polynomial:

$$FX = A_0 + A_1 \times X^{B_1} + A_2 \times X^{B_2} + \dots + A_n \times X^{B_n},$$

where A_i, B_i are sets, and X stands for a state space, a class of objects in base category.

- Then, a coalgebra is a mapping:

$$c : X \rightarrow FX,$$

where c is n -tuple of morphisms of category that causes change of state.

Language *E-Jane*

We extend the base language with new constructs:

- Declarations of variables (without initializations):

$$D ::= \text{var } x \mid \varepsilon$$

where ε is an empty declaration;

- block statement, user input and output statements:

$$S ::= \dots \mid \text{begin } D; S \text{ end} \mid \text{input } x \mid \text{print } e.$$

- A source program in *E-Jane* has a form

$$D_1; \dots; D_m; S_1; \dots; S_n,$$

so it consists of a list of declarations and a list of statements.

Signatures for lists of declarations and statem/ents

First, we specify signatures for the lists of declarations and statements:

$$\begin{aligned}\Sigma_{Decl_List} &= List_{fin} [Decl] \\ types : & \quad Decl_List, Decl \\ opns : & \\ & \quad init_d : \rightarrow Decl_List \\ & \quad head_d : Decl_List \rightarrow Decl \\ & \quad tail_d : Decl_List \rightarrow Decl_List\end{aligned}$$
$$\begin{aligned}\Sigma_{Statm_List} &= List_{fin} [Statm] \\ types : & \quad Statm_List, Statm \\ opns : & \\ & \quad init : \rightarrow Statm_List \\ & \quad head : Statm_List \rightarrow Statm \\ & \quad tail : Statm_List \rightarrow Statm_List\end{aligned}$$

Signature for memory

An abstraction of a memory we specify as a signature *Memory*:

$$\Sigma_{Memory} =$$

types : *Memory*, *Var*, *Value*
opns : *init* : $\rightarrow Memory$
alloc : *Var*, *Memory* $\rightarrow Memory$
get : *Var*, *Memory* $\rightarrow Value$
del : *Memory* $\rightarrow Memory$

- *init* establishes an initial memory of a program;
- *alloc* reserves a memory cell for declared variable;
- *get* returns (gets) an actual values of a variable;
- *del* deallocates (forgets) all memory cells defined on the highest nesting level.

Signature for configuration

In our approach, we will use *configuration* as a kind of state (snapshot of a memory) which we specify as follows:

$$\begin{aligned}\Sigma_{Config} = & \Sigma_{Decl.List} + \Sigma_{Statm.List} + \Sigma_{Memory} + \\ & types : Config \\ & opns : next : Config \rightarrow Config \\ & \quad input : Config, Value \rightarrow Config \\ & \quad print : Config \rightarrow Value, Config\end{aligned}$$

- *next* provides the next configuration;
- *input* takes an input value and stores it into the given (concrete) memory cell;
- *print* evaluates the value of an argument and returns it as an observable value.

Representation of types

We assign to particular specifications of types their representations as follows:

Type	Representation
<i>Value</i>	Value = $\mathbf{Z} \cup \{\perp\}$
<i>Var</i>	Var
<i>Decl_List</i>	Decl_List
<i>Statm_List</i>	Statm_List
<i>Memory</i>	Memory
<i>Config</i>	Config = Program \times Memory

$$\llbracket D^* \rrbracket = \llbracket D_1; \dots; D_n \rrbracket$$
$$\llbracket S^* \rrbracket = \llbracket S_1; \dots; S_n \rrbracket$$

Representation of a program is :

$$\mathbf{Program} = \llbracket D^*; S^* \rrbracket$$

and an initial configuration of a program is:

$$config_0 = (\llbracket D^*; S^* \rrbracket, m_0)$$

Representation of memory

We must to consider a level of nesting for a block statement:

$$l \in \mathbf{Level}, \text{ where } \mathbf{Level} \subseteq \mathbf{N}.$$

An actual memory $m \in \mathbf{Memory}$ we represent as a function:

$$m : \mathbf{Var} \times \mathbf{Level} \rightarrow \mathbf{Value}.$$

This function can be defined also by graph of a function:

$$\mathit{graph}(m) = \{((x, l), v) \mid m(x, l) = v\}.$$

We need an auxiliary function which returns the highest nesting level:

$$\begin{aligned} \mathit{maxlevel} : & \quad \mathbf{Memory} \rightarrow \mathbf{Level}, \\ \mathit{maxlevel}(m) = & \quad L, \text{ where } \forall l_j. L \geq l_j, \end{aligned}$$

for

$$\mathit{graph}(m) = \{((x_1, 1), v_1), \dots, ((x_i, l_j), v_k)\}.$$

Operations on a memory

An operation for initialization of memory we define as follows:

$$\llbracket init \rrbracket = m_0 = \{((\perp, 1), \perp)\}$$

variable	level	value
x_1	1	v_1
\vdots		
x_n	l	v_n

actual memory

variable	level	value
\perp	1	\perp

initial memory

Operations on a memory

The other operations in memory we define as follows:

$$\begin{aligned}\llbracket alloc \rrbracket(x, m) &= graph(m) \cup \{((x, maxlevel(m)), \perp)\} \\ \llbracket get \rrbracket(x, m) &= v, \quad \text{if } ((x, maxlevel(m)), v) \in m \\ \llbracket del \rrbracket m &= graph(m) \setminus \{((x_i, maxlevel(m)), v_i) \mid i \in \mathbf{N}\}\end{aligned}$$

variable	level	value
\vdots	\vdots	\vdots
x	l	\perp

allocation of memory

variable	level	value
\vdots	\vdots	\vdots
x	l_{j-1}	v
x_i	l_j	v_k
\vdots	\vdots	\vdots
x_n	l_j	v_m

forgetting of local variables

Representation of configurations

The last step is to define the representation of configurations. Configurations *config* are elements of the set **Config**:

$$\mathbf{Config} = \mathbf{Program} \times \mathbf{Memory}.$$

An initial configuration before the execution of a program has a form:

$$config_0 = (\llbracket D_1; D_2; \dots; D_m; S_1; S_2; \dots; S_n \rrbracket, m_0).$$

After every step of program execution:

- a configuration is changed, an operation $\llbracket tail \rrbracket$ is applied on a list of declarations and statements;
- memory can be changed, this depends on an elaborated declaration or executed statement.

Set **Config** is considered as a **state space** of coalgebra.

Semantics of declarations

Semantics of declarations is defined as a function on a memory:

$$\llbracket \text{var } x \rrbracket : \mathbf{Memory} \rightarrow \mathbf{Memory}$$

as

$$\llbracket \text{var } x \rrbracket m = \llbracket \text{alloc} \rrbracket (x, m).$$

We extend set of variables **Var** with special (dummy) variables `begin` and `end` to ensure that we can identify the beginning and the end of a block statement. Such declaration increments level of nesting and we define its elaboration as follows:

$$\begin{aligned} \llbracket \text{begin} \rrbracket m &= \text{graph}(m) \cup \{((\text{begin}, l + 1), \perp)\}, \\ \llbracket \text{end} \rrbracket m &= \llbracket \text{del} \rrbracket m. \end{aligned}$$

Extending the semantics of declarations for configurations

Because a state space of coalgebra is a set of configurations, we extend the definition for elaboration of declarations for configurations. We define a morphism:

$$\llbracket next \rrbracket : \mathbf{Config} \rightarrow \mathbf{Config},$$

and we define elaboration of declarations by the following functions:

$$\begin{aligned}\llbracket next \rrbracket(\llbracket \mathbf{var} \ x; D^*; S^* \rrbracket, m) &= (\llbracket D^*; S^* \rrbracket, \llbracket \mathbf{var} \ x \rrbracket m), \\ \llbracket next \rrbracket(\llbracket \mathbf{begin} \ D^*; S' \ \mathbf{end}; S^* \rrbracket, m) &= (\llbracket D^*; S' \ \mathbf{end}; S^* \rrbracket, \llbracket \mathbf{begin} \rrbracket m) \\ \llbracket next \rrbracket(\llbracket \mathbf{end}; S^* \rrbracket, m) &= (\llbracket S^* \rrbracket, \llbracket \mathbf{end} \rrbracket m).\end{aligned}$$

This definition corresponds with the traditional definition for elaboration of declarations, where the declaration of a variable actualizes an environment of variables.

Semantics of statements

An execution of one step we define with the morphism $\llbracket next \rrbracket$:

$$\llbracket next \rrbracket : \mathbf{Config} \rightarrow \mathbf{Config}.$$

For an assignment statement and for the statement `skip`, this morphism is defined as follows:

$$\begin{aligned}\llbracket next \rrbracket(\llbracket x := e, S^* \rrbracket, m) &= (\llbracket S^* \rrbracket, m[((x, l), v) \mapsto ((x, l), \llbracket e \rrbracket m)]) \\ \llbracket next \rrbracket(\llbracket \mathbf{skip}; S^* \rrbracket, m) &= (\llbracket S^* \rrbracket, m)\end{aligned}$$

In the sequence of statements, any statement can be executed in one or more steps. Hence we must to consider the following situations:

$$\llbracket next \rrbracket(\llbracket S_i; S_{i+1}; \dots; S_n \rrbracket, m) = \begin{cases} (\llbracket S_{i+1}; \dots; S_n \rrbracket, m'), & \text{if } \langle S_i, m \rangle \Rightarrow m'; \\ (\llbracket S'_i; S_{i+1}; \dots; S_n \rrbracket, m'), & \text{if } \langle S_i, m \rangle \Rightarrow \langle S'_i, m' \rangle. \end{cases}$$

Semantics of statements

An execution of conditional statement depends on a value of Boolean condition. Hence we define the first step of execution as follows:

$$\llbracket next \rrbracket(\llbracket \text{if } b \text{ then } S'_i \text{ else } S''_i; S_{i+1}; \dots; S_n \rrbracket, m) = \begin{cases} (\llbracket S'_i; S_{i+1}; \dots; S_n \rrbracket, m), & \text{if } \llbracket b \rrbracket m = \mathbf{true}; \\ (\llbracket S''_i; S_{i+1}; \dots; S_n \rrbracket, m), & \text{if } \llbracket b \rrbracket m = \mathbf{false}. \end{cases}$$

The first step of execution of a loop is a transformation to the semantically equivalent conditional statement, and we define this step as follows:

$$\begin{aligned} & \llbracket next \rrbracket(\llbracket \text{while } b \text{ do } S'_i; S_{i+1}; \dots; S_n, m \rrbracket) \\ &= \llbracket next \rrbracket(\llbracket \text{if } b \text{ then } S'_i; \text{while } b \text{ do } S'_i \text{ else skip}; S_{i+1}; \dots; S_n \rrbracket, m) \end{aligned}$$

Semantics of statements

For the statements of user input and output, we define appropriate representations of the operations in signature for configurations:

$$\llbracket \text{input} \rrbracket(\llbracket \text{input } x; S_{i+1}; \dots; S_n \rrbracket, m) = \lambda v'.(\llbracket S_{i+1}; \dots; S_n \rrbracket, m'),$$

where m' is an actualized memory

$$m' = m[((x, \text{maxlevel}(m)), v) \mapsto ((x, \text{maxlevel}(m)), v')],$$

where an input value v is stored into a memory cell allocated for the variable x on the highest nesting level.

The output statement does not change a memory, but it changes a configuration (output statement is removed from the sequence of statements):

$$\llbracket \text{print} \rrbracket(\llbracket \text{print } e; S_{i+1}; \dots; S_n \rrbracket, m) = (\llbracket e \rrbracket m, (\llbracket S_{i+1}; \dots; S_n \rrbracket, m))$$

Semantics of statements

During the execution of a block statement, an elaboration of a special variable `begin` is elaborated:

$$\llbracket next \rrbracket(\llbracket \mathbf{begin} \ D^*; S'_i \ \mathbf{end}; S_{i+1}; \dots; S_n \rrbracket, m) = \\ (\llbracket D^*; S'_i \ \mathbf{end}; S_{i+1}; \dots; S_n \rrbracket, \llbracket begin \rrbracket m)$$

and an execution of a block statement continues by elaboration of real local variables (if present) and by execution of statements inside a block.

For an interruption of program execution we define a function

$$abort : \mathbf{Config} \rightarrow \mathbf{Config},$$

which immediately terminates running program which ends in an undefined configuration $config_{\perp}$:

$$abort(config) = (\varepsilon, m_{\perp}),$$

Base category for coalgebra

We construct a category \mathcal{Config} where:

- configurations $config = (\llbracket D^*; S^* \rrbracket, m)$ are category objects;
- mappings $\llbracket next \rrbracket, \llbracket input \rrbracket, \llbracket print \rrbracket$ and $abort$ are category morphisms;
- we define an identity morphism for each configuration;
- composition of morphisms and associativity of composition holds.

An undefined configuration is also a terminal (final) object of a category:

$$config_{\perp} = (\varepsilon, m_{\perp})$$

because there exists a possibility to abrupt the program execution from any configuration.

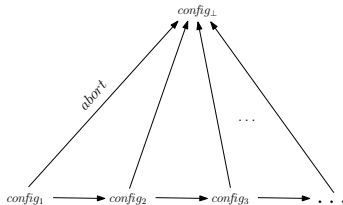
Colimit in base category

In case of infinite loop we must to guarantee that an execution of such a statement cannot be defined in category. Hence we require that each infinite path in category must to have a colimit:

- Let $config_1 \rightarrow config_2 \rightarrow config_3 \rightarrow \dots$ be an infinite path (diagram \mathcal{D}) in category;
- object $config_{\perp}$ is a colimit of diagram \mathcal{D}

$$\text{colimit } \mathcal{D} = \bigcirc_{i \in \mathbb{N}} \llbracket next \rrbracket (\llbracket \text{while } b \text{ do } S; S^* \rrbracket, m)$$

if from every object exists a morphism into this object.



Coalgebra

- We have constructed base category \mathcal{Config} , which objects are configurations $config$ and morphisms are $\llbracket next \rrbracket, \llbracket input \rrbracket, \llbracket print \rrbracket$.
- We construct an appropriate form of polynomial endofunctor which will characterize this kind of systems:

$$Q : \mathbf{Config} \rightarrow \mathbf{Config},$$
$$Q(\mathbf{Config}) = 1 + \mathbf{Config} + O \times \mathbf{Config} + \mathbf{Config}^I.$$

- Coalgebra is defined as $c : X \rightarrow FX$ in general; we assign our state space and morphisms, then a coalgebra for programs in language *E-Jane* has a form:

$$\langle abort, \llbracket print \rrbracket, \llbracket next \rrbracket, \llbracket input \rrbracket \rangle : \mathbf{Config} \rightarrow Q(\mathbf{Config}).$$

Coalgebra models the behavior of a program such that in each step one of the following alternatives occurs:

- $Q(\mathbf{Config}) = 1$ – program aborts;
- $Q(\mathbf{Config}) = \mathbf{Config}$ elaborates a declaration/executes a statement;
- $Q(\mathbf{Config}) = O \times \mathbf{Config}$ provides an output value;
- $Q(\mathbf{Config}) = \mathbf{Config}^I$ takes an input value.

Example

We consider a program in language *E-Jane*:

```
var x; var y;  
input x; input y;  
if x <= y then begin  
    var z;  
    z := x; x := y; y := z  
end  
else skip;  
print x
```

For simplicity we introduce the following substitutions:

$$\begin{aligned} D_1 &= \text{var } x; D_2 = \text{var } y; \\ S_1 &= \text{input } x; S_2 = \text{input } y; \\ S_3 &= \text{if } x \leq y \text{ then begin var } z; \\ &\quad z := x; x := y; y := z \text{ end else skip} \\ S_4 &= \text{print } x \end{aligned}$$

and we consider values **3** and **5** for variables *x* and *y*, resp.

Example

An initial configuration is $config_0 = (\llbracket D_1; D_2; S_1; S_2; S_3; S_4 \rrbracket, m_0)$.
Every application of functor Q represents one step of program execution:

$$\begin{aligned} Q(config_0) &= \llbracket next \rrbracket(config_0) = \\ &= (\llbracket D_2; S_1; S_2; S_3; S_4 \rrbracket, \llbracket var\ x \rrbracket(x, m_0)) = \\ &= config_1 \end{aligned}$$

$$\begin{aligned} Q(config_1) &= \llbracket next \rrbracket(config_1) = \\ &= (\llbracket S_1; S_2; S_3; S_4 \rrbracket, \llbracket var\ x \rrbracket(y, m_0)) = \\ &= config_2 \end{aligned}$$

$$\begin{aligned} Q(config_2) &= \llbracket input \rrbracket(\llbracket S_1; S_2; S_3; S_4 \rrbracket, m_0) = \\ &= (\llbracket S_2; S_3; S_4 \rrbracket, m_1) = config_3 \end{aligned}$$

$$\begin{aligned} Q(config_3) &= \llbracket input \rrbracket(\llbracket S_2; S_3; S_4 \rrbracket, m_1) = \\ &= (\llbracket S_3; S_4 \rrbracket, m_2) = config_4 \end{aligned}$$

Example

$$Q(\text{config}_4) = \llbracket \text{next} \rrbracket(\llbracket \text{begin var } z; z := x; x := y; y := z \text{ end}; S_4 \rrbracket, m_2) = (\llbracket \text{var } z; z := x; x := y; y := z \text{ end}; S_4 \rrbracket, \llbracket \text{begin} \rrbracket m_2) = \text{config}_5$$

$$Q(\text{config}_5) = \llbracket \text{next} \rrbracket(\llbracket \text{var } z; z := x; x := y; y := z \text{ end}; S_4 \rrbracket, m_2) = (\llbracket z := x; x := y; y := z \text{ end}; S_4 \rrbracket, \llbracket \text{var } x \rrbracket(z, m_3) = \text{config}_6$$

$$Q(\text{config}_6) = \llbracket \text{next} \rrbracket(z := x; x := y; y := z \text{ end}; S_4 \rrbracket, m_3) = (\llbracket x := y; y := z \text{ end}; S_4 \rrbracket, m_4) = \text{config}_7$$

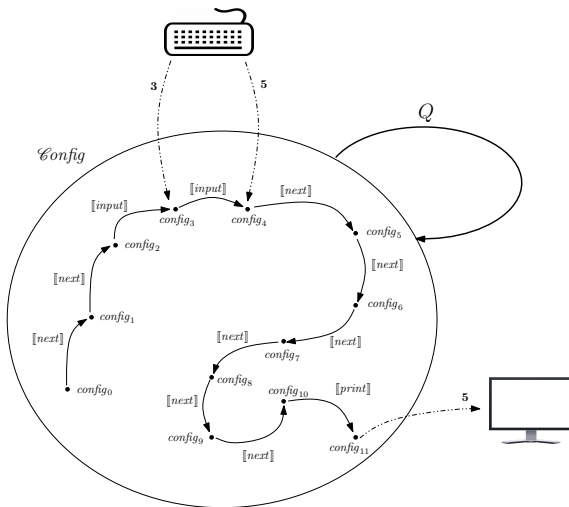
$$Q(\text{config}_7) = \llbracket \text{next} \rrbracket(\llbracket x := y; y := z \text{ end}; S_4 \rrbracket, m_4) = (\llbracket y := z \text{ end}; S_4 \rrbracket, m_5) = \text{config}_8$$

$$Q(\text{config}_8) = \llbracket \text{next} \rrbracket(\llbracket y := z \text{ end} \rrbracket, m_5) = (\llbracket \text{end}; S_4 \rrbracket, m_6) = \text{config}_9$$

$$Q(\text{config}_9) = \llbracket \text{next} \rrbracket(\llbracket \text{end}; S_4 \rrbracket, m_6) = (\llbracket S_4 \rrbracket, \llbracket \text{end} \rrbracket m_6) = \text{config}_{10}$$

$$Q(\text{config}_{10}) = \llbracket \text{print} \rrbracket(\llbracket S_4 \rrbracket, m_6) = (\mathbf{5}, (\varepsilon, m_6)) = \text{config}_{11}$$

Example



Thank you for your attention.